

First lessons learnt from Metop

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Initial Joint Polar System

- Since 1978 NOAA is flying operational polar orbiting weather satellites carrying multi-spectral sounders and imagers
- Under a NOAA-EUMETSAT cooperation agreement, signed in November 1998, Europe agreed to share the burden of the meteorological polar service with the USA
- Integration and coordination of the NOAA Polar Orbiting Environmental Satellite (POES) and the EUMETSAT Polar System (EPS) Programmes:
 - Afternoon & early morning orbits covered by the USA (POES & DMSP Satellites)
 - Mid-morning orbit covered by Europe (Metop Satellites)
 - Exchange of instruments and data, coordinated development and operations

Joint effort in a partnership of ESA, NOAA, CNES, and EUMETSAT



Start from Cosmodrome in Baikonour with Sojuz/Fregat launcher on 19 October 2006



...overpass of Metop, observed by Dieter Klaes on 19 April 2007

MetOp-A

6/2 MESZ

. . © Dieter Klaes



Height: 6.3 m Transverse Section: 3.4 m x 3.4 m (Launch Configuration)

Solar Panel: 11.3 m

Power: 2210 W (End of Life, Orbit Average)

Lifetime: 5 Years

12 Instruments

Launch Mass: 4200 kg

Data Flow: 3500 kbps

The Metop Satellite



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Metop during integration of instruments





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From launch to operational use (1/2)

Launch on 19 October 2006 from Cosmodrome in Baikonur

- Start and transfer to final orbit by ESA/ESOC
- Handover to EUMETSAT: 22 October 2006
- Successive switch-on of instruments and distribution of data
 - SARR, SARP instrument switch on: 24 October 2006
 - AMSU-A1/A2 instrument switch-on: 24 October 2006
 - First global AMSU-A data distributed in NRT: 31 October 2006
 - IASI instrument switch-on and start of otgassing: 24 October 2006
 - AVHRR instrument switch-on and outgassing: 25 October 2006
 - First generation of AVHRR L1 products (VIS, NIR): 25 October 2006
 - HIRS instrument switch-on and outgassing: 26 October 2006
 - A-DCS instrument switch-on: 26 October 2006
 - GRAS instrument switch-on: 27 October 2006
 - ASCAT instrument switch-on and first product generated: 27 October 2006



From launch to operational use (2/3)

Successive switch-on of instruments and distribution of data (cont.)

- GOME-2 instrument switch-on: 27 October 2006
- GOME-2 first spectra: 30 October 2006
- MHS instrument switch-on and first data: 31 October 2006
- MHS first L1 products generated: 1 November 2006
- SEM instrument switch-on: 9 november 2006
- ASCAT in measurement mode: 20 November 2006
- A-DCS instrument switch-on: 20 November 2006
- AVHRR, HIRS, GOME-2 in measurement mode:
- LRPT switch-on: 15 January 2007
- AHRPT switch-on: 23 January 2007
- LRPT switch-off permanently (RFI with HIRS): 26 January 2006
- 4 November 2006: Two anomalies abruptly stopped the sequence of success
 - Sudden failure within the Low Resolution Picture Transmitter (LRPT)
 - Sudden automatic switch-off of the complete Metop-A Payload Module, with all instruments.



From launch to operational use (3/3)

Progressive dissemination of data to users

- Monitoring by NWP centres (ECMWF and Met Offcie) provides valuable information on data quality and anomalies
- First global AMSU-A data distributed in NRT: 31 October 2006
- Met Office starts assimilation of AMSU-A data on 22 January 2007
- ECMWF starts assimilation of IASI data on 12 May 2007
- Cooperation with OSI SAF leads to successful calibraton of ASCAT despite failure of calibration transponders
- Completion of Metop-A Satellite In-Orbit Verification (SIOV): 30 March 2007
- Hand-over to operations: 21 May 2007



Metop-A control during SIOV





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Metop-A Satellite In-Orbit Verification



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Validation

- Validation of processors and products
 - Configuration of Product Processing Facilities
 - First rough validation including bias corrections in Level 2 processors using short-range forecasts
 - Refinement wit data from dedicated validation campaigns
- Campaigns:
 - ASCAT transponder-campaign Turkey, November 2007
 - CNES/CNRS IASI-Balloon: Kiruna, February 2007
 - Met Office FAAM: Western North Sea, March2007
 - IfM/Polarstern: Atlantic Ocean, April/May 2007
 - Met Office/NASA FAAM and WB-57: Golf of Mexiko and Oklahoma ARM-Site, April/May 2007
 - DWD: Assmann-Observatory Lindenberg, June-August 2007
 - FMI: Observatory Sodankylä, June-August 2007
 - CNES/CNRS IASI-Balloon: Kiruna, September 2007



Partnership (1/2)

- The EPS programme was set up in partnership with
 - ESA (for the development of the Metop space Segment)
 - NOAA (provision of US instruments and operational cross support)
 - CNES-IASI (Development of the IASI instrument, level 1 processor and Technical Expertise Centre)
 - CNES-ARGOS (A-DCS payload and operations)
- The Space Segment development was managed by the Single Space Segment Team (SSST) located at ESTEC, Noordwijk
- The Metop-A satellite was developed by a European consortium led by Astrium as the prime contractor under a joint ESA-EUMETSAT contract
- The Launch service was provided by Starsem using a Soyuz 2.1 a with an ST fairing launcher from the Baikonur Cosmodrome, under EUMETSAT Contract



Partnership (2/2)

- The Launch and Early Operations Phase (LEOP) was conducted by ESOC, Darmstadt, under EUMETSAT contract
- The Core Ground Segment was developed by Thales Alenia Space under EUMETSAT contract
- The Satellite SIOV activities were conducted by a joint team led by the SSST, EUMETSAT being responsible for the operations, and with contributions from all other partner organisations and industrial teams from the space segment and instrument manufacturers
 - Last but not least: EUMETSAT users provide valuable feedback
 - Throughout the programme development on instrument characteristics, system configurations, product processing and product formats
 - Post-launch via data monitoring and data usage



Satellite Application Facilities (SAF)





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EPS Service

Local Mission: Real-time data transfer of imaging and sounding instruments to local receiving stations

Global Mission: Provision of global data from Metop and NOAA satellites within 2¼ hours after respective measurements

Search and Rescue (S&R) Relay of distress signals

A-DCS: Reception and transfer of in-situ data



Daten Dissemination: EUMETCast: full data stream GTS: sub-set

IASI TEC CNES Toulouse IASI-Cal/Val and monitoring UMARF Central archive

EUMETSAT -

Data transfer and distribution

- From satellite to surface:
 - Data of one orbit is stored on board the satellite
 - Transfer to surface via X-band reception station on Svalbard after completion of each orbit
 - Transfer from Svalbard to Darmstadt via fibre link
 - Local users can directly read out the instrument data while the satellite is above their horizon
- Data processing in EPS Core Ground Segment at EUMETSAT HQ
 - Generation of Level-1-Products: decoding, calibration, navigation, apodisation, mapping/merging of data from different instruments
 - Generation of ATOVS and IASI Level-2-Products: atmospheric and surface meteorological parameters
- Distribution to users:
 - Level 1: within 2¹/₄ h after measurement, Level 2: within 3 h after measurement
 - Transfer via EUMETCast (BUFR code)
 - Transfer of subset via GTS (BUFR code)
 - All data, inclusive generated products are archived in the UMARF: Unified Archival and Retrieval Facility, and accessible 7 hours after the measurement



ATOVS- and AVHRR-Products

- AVHRR: Advanced Very High Resolution Radiometer
- AMSU-A: Advanced Microwave Sounding
- MHS: Microwave Humidity Sounder
- HIRS: High-resolution Infrared Radiation Sounder





EUMETSAT

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AVHRR SE-Coast of Greenland on 16/03/2007







AVHRR:

Wind vectors vectors in polar regions

CIMSS/Univ. Wisconsin



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MHS

MHSx_xxx_00_M02_20061031123900Z_20061031141800Z_N_C_20061031141551Z













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Feedback from Met Office AMSU-A noise figures (NE∆T in K)

Channel	Spec	Met Office estimate	NOAA- 18	Channel	Spec	Met Office estimate	NOAA- 18
1	0.3	0.19	0.20	9	0.25	0.18	0.17
2	0.3	0.19	0.18	10	0.4	0.24	0.20
3	0.4	0.28	0.22	11	0.4	0.29	0.23
4	0.25	0.15	0.16	12	0.6	0.37	0.29
5	0.25	0.15	0.18	13	0.8	0.52	0.40
6	0.25	0.12	0.15	14	1.2	0.92	0.63
7	0.25	0.13	0.16	15	0.5	0.10	0.14
8	0.25	0.19	0.20				



Feedback from Met Office MHS noise figures (NE∆T in K)

Channel	Spec	EUMETSAT estimate	Met Office estimate	NOAA-18 EUM/NOAA	AMSU-B EUM/NOAA
1	1.0	0.19	0.20	0.21/0.32	0.41/040
2	1.0	0.39	0.37	0.34/0.53	0.80/0.80
3	1.0	0.52	0.50	0.54/0.50	0.82/0.80
4	1.0	0.40	0.41	0.40/0.41	0.75/0.75
5	1.0	0.36	0.34	0.55/0.55	0.80/0.80





HIRS Channel 8

21 November 2006



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ASCAT: Advanced Scatterometer



LEVEL 2: soil moisture (land)



LEVEL 2: surface wind (ocean)

ASCAT: 20070530 21:30Z HIRLAM: 2007053015+6 lat ion: 61.76 -3.41 IR: 21:30

ASCA_SZO_1B_M02_20070530195702Z_20070530213559Z_N_O_20070530214303Z

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Page 35

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ASCAT

Normalised backscatter coefficients (σ_0)





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ASCAT: first comparisons by ECMWF



• GOME-2: Global Ozone Monitoring Experiment 2

First GOME-2 ozone columnar contents



First GOME-2 NO₂ columnar contents





Loyola, 2007

10¹⁶ mol cm⁻²

10¹⁵ mol cm⁻²



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GRAS GAVA antenna

Global Receiver for Atmospheric Sounding





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Infrared Atmospheric Sounding Interferometer (IASI)

- Michelson-Interferometer •
- IFOV diameter
- Scan interval (horiz.) •
- Swath width \bullet
- Spectral domain
- Spectral resolution
- Radiometric resolution Absolute calibration
 - Data rate
 - Internal imager

8461 spectral samples 12 km (nadir) 25 km (nadir) ±48.33° (2200 km) 645 - 2760 cm⁻¹ (3.6 – 15.5 μm) 0.5 cm⁻¹ 0.07 - 0.7 K (bands 1, 2) < 0.3 K 1.5 Mbit/s 10-12 µm Temperature- and humidity profiles, O₃, CO, CO₂, CH₄, N₂O, ...



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IASI FM-2: Radiometric noise



Scan patterns of the instruments





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IASI Level 2 product generation

ATOVS Level 2			MHS Lovel 1	NIWP Forecast
ATOVO LEVELZ		ANIOU-A Level 1		Itwi i biecast
		Pre-Pro	cessing	
			J	
		Cloud Pro	ocessing	
	G	eophysical Para	ameters Retrie	val
Monitoring Information		Level 2 Pro	duct	Quality Information

Properties of the Operational IASI L2 Processor (1/3)

- For a best use of IASI measurements the level 2 processing can combine IASI with concurrent measurements of AVHRR, AMSU-A, MHS, and ATOVS Level 2 products
- IASI stand-alone processing is possible if other measurements are not available, or if Product Processing Facility is explicitly configured to exclude other instruments
- NWP forecast is included to provide surface pressure as reference for the profiles to be retrieved and surface wind speed over sea for the calculation of surface emissivity
- Optionally, the NWP forecast profiles of temperature, water vapour and ozone can be used to initialise and/or constrain the retrieval



Properties of the Operational IASI L2 Processor (2/3)

- Processing is steered by configuration settings (80 configurable auxiliary data sets), which allows for optimisation of Product Processing Facility before and during commissioning
- Online quality control supports the choice of best processing options in case of partly unavailable IASI data or corrupt side information (data from other instruments or NWP forecast)
- Besides error covariances a number of flags are generated steering through the processing and giving quality indicators; 40 flags are specified, which are part of the product



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Properties of the operational IASI L2 Processor (3/3)

- All 8461 IASI spectral samples, covering the spectral region from 645 to 2760 cm⁻¹, are used in the retrieval to maximise the retrieved information
- The Product Processing Facility supports nominal and degraded instrument modes (e.g. failure of single detectors/bands)
- Bias control by radiance tuning via configuration



Cloud processing

Cloud detection

- AVHRR-based cloud detection using Scenes Analysis from AVHRR Level 1 processing
- Combined IASI / ATOVS cloud detection
- IASI stand-alone cloud detection
- Cloud parameters retrieval
 - Cloud fraction
 - Cloud top height
 - Cloud phase



First IASI spectra on 29 November 2006



IASI - 645 cm⁻¹



IASI - 945 cm⁻¹



IASI - 1645 cm⁻¹



Comparisons of simulated and measured spectra





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Comparisons of simulated and measured spectra





Correction of systematic errors

 ΔT_B (OBS-MOD) mean and stddev

- All retrieval and assimilation schemes use radiative transfer calculations as basis
- Prerequisite for the functionality of the retrieval or assimilation is a good representativity of the measurements by simulated radiances
 - Systematic errors:
 - Approxmations necessary for fast calculations
 - Insufficient knowledge of spectroscopic data
 - Erroneous input data
- Systematic fit of models to IASI measurements



$\rm AVHRR/0.6,$ cold front, all CFR, IASI 20070418124454Z



Discrimination of ice and water clouds



Geophysical parameters retrieval: state vector to be retrieved

- The state vector to be retrieved consists of the following parameters
 - Temperature profile at a minimum of 40 levels
 - Water vapour profile at a minimum of 20 levels
 - Ozone columns in deep layers (0-6km, 0-12 km, 0-16 km, total column)
 - Land or sea surface temperature
 - Surface emissivity at 12 spectral positions
 - Columnar amounts of N_2O , CO, CH₄, CO₂
 - Cloud amount (up to three cloud formations)
 - Cloud top temperature (up to three cloud formations)
 - Cloud phase

In case of clouds and elevated surface the state vector has to be modified



Geophysical parameters retrieval: first retrieval

- Spectra PC scores regression for temperature and water-vapour, and ozone profiles, surface temperature, and surface emissivity
- Artificial neural network (multi-layer perceptron) for trace gases (optionally also for temperature, water-vapour and ozone, depends on configuration setting)
- The results from the first retrieval may constitute the final product or may serve as input to the final, iterative retrieval; the choice depends on configuration setting and on quality of the first retrieval results



Geophysical paramters retrieval: final, iterative retrieval

- Simultaneous iterative retrieval, seeking maximum probability solution for minimisation of cost function by Marquardt-Levenberg method, using a subset of IASI channels, single or combined to super-channels
- Initialisation with results from first retrieval
- Other choices of initialisation may be selected, depending on configuration setting and availability (e.g. NWP forecast, climatology, ATOVS Level 2 product)
- Background state vector from climatology, ATOVS Level 2 product, adjacent retrieval, or NWP forecast, depending on configuration and availability
- State vector to be iterated depends on cloud conditions and configuration setting (clear, cloudy, variational cloud clearing)



Comparison: IASI / NAST-I / radiosonde



EUMETSAT



Comparison: ECMWF / IASI Clear situations May – June 2007 Land: 1330 match-ups Ocean: 21810 match-ups



Comparison: ECMWF – IASI L2



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JAIVEx: Joint Airborne IASI Validation Experiment







IASI: temperature retrievals on 10 June 2007 ~09:30 UTC

Page 69

IASI: temperature retrievals on 10 June 2007 ~09:30 UTC





IASI: humidity retrievals on 10 June 2007 ~09:30 UTC




IASI level 1 data format

Advantages of current data format

- User can use the IASI spectra like those from channel radiometers and extract useful parts
- Interferometric characteristics are hidden from users, e.g. negative radiances

Disadvantages of current data format

- Large data volume: 2 Mbit/s
- Quantisation in 16 bit words: slight degradation
- Full usage of information hardly possible
- Apodisation of spectra implies non-diagonal error covariances: complication in assimilation and retrieval



Possible future representation

Utilisation of empirical orthogonal functions

- Projection of IASI level 1A spectra (unapodised) on ~250 EOFs
- Dissemination of EOF-scores

Advantage and new potential

- Data volume: 49 kbit/s
- Re-constructed spectra are quasi noise-free
- Direct assimilation of EOF scores instead of radiance spectra



Conclusion

- Metop-A has been launched and been operated successfully
- New instruments have been successfully commissioned
- Level 1 data are routinely disseminated to users
- Validation of the numerous products is ongoing



PCRTM: radiative transfer in EOF-space

PCRTM calculates EOF-scores (Y) instead of spectral radiances (R)

$$\vec{Y} = U \times \vec{R}^{mono}$$
$$\frac{\partial Y_i}{\partial X} = \sum_{l=1}^{N_{mono}} a_l \frac{\partial R^{mono}(l)}{\partial X}$$

• Relationship between EOF scores and measured radiances:

$$R_{i}^{chan} = \frac{\sum_{k=1}^{N} \phi_{k} R_{k}^{mono}}{\sum_{k=1}^{N} \phi_{k}}; \qquad \vec{Y} = U^{T} \times \vec{R}^{chan}$$

Spectral radiances can be calculated from EOFs and corresponding scores:

$$\vec{R}^{chan} = U \times \vec{Y} = \sum_{i=1}^{N_{EOF}} y_i \vec{U}_i + \vec{\varepsilon}$$



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PCRTM: Training with LBL-model

•RMS error in brightness temperature: < 0.025 K

•Systematic errors in brightness temperature: (-0.0002 K, 0.0004 K)





PCRTM: validation with ECMWF and IASI data





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PCRTM-retrieval: Levenberg-Marquardt-iteration

$$X_{n+1} - X_{a} = (K^{T} S_{y}^{-1} K + \lambda I + S_{a}^{-1})^{-1} K^{T} S_{y}^{-1} [(Y_{n} - Y_{m}) + K (X_{n} - X_{a})]$$

50 retrieved EOF-Scores:

Surface temperature: 1 Temperature profile: 19 Humidity profile: 15 Ozone profile:10 Emissivity: 5

Variable	Radiance/state vector: dimensions	EOF-space: dimensions
Y	8461	100
X	>100	50
K	> 8461x100	100x50
S _y ⁻¹	8461x8461	100x100
S _a	> 100x100	50x50
Calculation of <i>K</i> and <i>Y</i>	~2 s	~0.1 s

